

6.4

Shortest Paths and Transitive Closure

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Single Source Shortest Paths

- Given a **digraph** with **nonnegative edge costs**, we want to compute the **shortest path** from a source vertex to all other vertices.
- Single source/all destinations** problem.

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Paths from 0 to 1:
 $0 \rightarrow 1 : 50$
 $0 \rightarrow 2 \rightarrow 4 \rightarrow 1 : 95$
 \dots
 $0 \rightarrow 3 \rightarrow 4 \rightarrow 1 : 45$

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Dijkstra's Algorithm



- Similar to Prim's algorithm
- Use a set S store the vertices whose shortest path have been found
- Use an array $dist$ store the shortest distances from source v to all visited vertices
- The algorithm
 - Let $S = \{v\}$, all entries in $dist = \infty$
 - For each vertex w not in S , update $dist_{w,w} = min(dist[u] + length((u,w)), dist[w])$
 u is the newly added vertex to S adjacent to w
 - Add to S the vertex x not in S but of the minimum cost in $dist$.
 - Repeat last two steps until S include all vertices.

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Running Example

S	0	1	2	3	4	5
{0}	0	50	45	10	∞	∞
{0, 3}	0	50	45	10	25	∞
{0, 3, 4}	0	45	45	10	25	∞
{0, 3, 4, 1}	0	45	45	10	25	∞
{0, 3, 4, 1, 2}	0	45	45	10	25	∞

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Running Example 2: 1/3

S	0	1	2	3	4	5	6	7
{4}	∞	∞	∞	1500	0	250	∞	∞
{4, 5}	∞	∞	∞	1250	0	250	1150	1650
{4, 5, 6}	∞	∞	∞	1250	0	250	1150	1650

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Running Example 2: 2/3

S	0	1	2	3	4	5	6	7
{4, 5, 6}	∞	∞	∞	1250	0	250	1150	1650
{4, 5, 6, 3}	∞	∞	2450	1250	0	250	1150	1650
{4, 5, 6, 3, 7}	3350	∞	2450	1250	0	250	1150	1650

Running Example 2: 3/3

S	0	1	2	3	4	5	6	7
{4, 5, 6, 3, 7}	3350	∞	2450	1250	0	250	1150	1650
{4, 5, 6, 3, 7, 2}	3350	3250	2450	1250	0	250	1150	1650
{4, 5, 6, 3, 7, 2, 1}	3350	3250	2450	1250	0	250	1150	1650
{4, 5, 6, 3, 7, 2, 1, 0}	3350	3250	2450	1250	0	250	1150	1650

Dijkstra's Algorithm

```

1. void MatrixWDigraph::ShortestPath(const int n, const int v)
2. { // dist[j], 0 ≤ j < n, stores the shortest path from v to j
3.   // length[i][j] stores length of edge i<-, j>
4.   for(int i=0; i<n; i++){ s[i]=false; dist[i]=length[v][i]; }
5.   s[v] = true;
6.   dist[v] = 0;
7.   // find n - 1 paths starting from v
8.   for(int i=0; i<n-1 ;i++){ -----> O(n)
9.     // Choose a vertex u, such that dist[u]
10.    // is minimum and s[u] = false
11.    int u = Choose(n); -----> O(n)
12.    s[u] = true;
13.    for(int w=0; w<n; w++) -----> O(n)
14.      if(s[w] && dist[u] + length[u][w] < dist[w])
15.        dist[w] = dist[u] + length[u][w];
16.   } // end of for (i = 0; ...

```

Time complexity: $O(n^2)$

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Digraph with Negative Costs

- This algorithm also applies to digraph with negative cost edges.
- However, the digraph **MUST NOT** contain cycles of negative length.

Digraph with a negative cost edge Digraph with a cycle of negative cost

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All-Pairs Shortest Paths

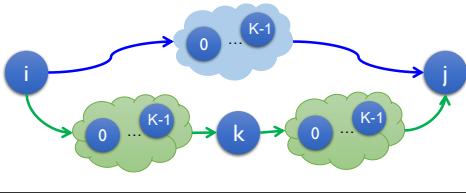
- Apply the single source shortest path to each of n vertices.
- Floyd-Warshall's algorithm
 - $A^{-1}[i][j]$: is just the $\text{length}[i][j]$
 - $A^{n-1}[i][j]$: the length of the shortest i -to- j path in G
 - $A^k[i][j]$: the length of the shortest path from i to j going through no intermediate vertex of index greater than k .
 - $A^k[i][j] = \min\{A^{k-1}[i][j], A^{k-1}[i][k] + A^{k-1}[k][j]\}, k \geq 0$

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Floyd-Warshall's Algorithm

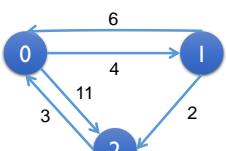
- There are only two possible paths for $A^k[i][j]$!
 - The path dose not pass vertex k .
 - The path dose pass vertex k .

$$A^k[i][j] = \min\{A^{k-1}[i][j], A^{k-1}[i][k] + A^{k-1}[k][j]\}, k \geq 0$$



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Example



A^{-1}	0	1	2
0	0	4	11
1	6	0	2
2	3	∞	0

$$A^0[2][1] = \min(A^{-1}[2][1], A^{-1}[2][0] + A^{-1}[0][1]) \\ = \min(\infty, 3 + 4) = 7$$

$$A^0[1][2] = \min(A^{-1}[1][2], A^{-1}[1][0] + A^{-1}[0][2]) \\ = \min(2, 6 + 11) = 2$$

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Example

A^0	0	1	2
0	0	4	11
1	6	0	2
2	3	7	0

$$A^1[2][0] = \min(A^0[2][0], A^0[2][1] + A^0[1][0])$$

$$= \min(3, 7 + 6) = 3$$

$$A^1[0][2] = \min(A^0[0][2], A^0[0][1] + A^0[1][2])$$

$$= \min(11, 4 + 2) = 6$$

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Example

A^1	0	1	2
0	0	4	6
1	6	0	2
2	3	7	0

$$A^2[0][1] = \min(A^1[0][1], A^1[0][2] + A^1[2][1])$$

$$= \min(4, 6 + 3) = 4$$

$$A^2[1][0] = \min(A^1[1][0], A^1[1][2] + A^1[2][0])$$

$$= \min(6, 2 + 3) = 5$$

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Example

A^2	0	1	2
0	0	4	6
1	5	0	2
2	3	7	0

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Floyd-Warshall's Algorithm

```

1. void MatrixWDigraph::AllLengths(const int n)
2. { // length[n][n] stores edge length between
   // adjacent vertices
3.   // a[i][j] stores the shortest path from i to j
4.   for (int i = 0; i<n; i++) -----> O(n)
5.     for (int j = 0; j<n; j++) -----> O(n)
6.       a[i][j] = length[i][j];
7.
8.   // path with top vertex index k
9.   for (int k = 0; k<n; k++) -----> O(n)
10.  // all other possible vertices
11.  for (int i = 0; i<n; i++) -----> O(n)
12.    for (int j = 0; j<n; j++) -----> O(n)
13.      if((a[i][k]+a[k][j])<a[i][j])
14.        a[i][j] = a[i][k] + a[k][j];
15. }

```

Time complexity: $O(n^3)$

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Transitive Closure

- The **transitive closure matrix** A^+ :
 - A^+ is a matrix such that $A^+[i][j] = 1$ if there is a **path of length > 0 from i to j** in the graph; otherwise, $A^+[i][j] = 0$.
 - The **reflexive transitive closure matrix** A^* :
 - A^* is a matrix such that $A^*[i][j] = 1$ if there is a **path of length ≥ 0 from i to j** in the graph; otherwise, $A^*[i][j] = 0$.
 - Use Floyd-Warshall's algorithm!

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Example: Transitive Closure



A ⁺	0	1	2	3
0	0	1	1	1
1	0	1	1	1
2	0	1	1	1
3	0	0	0	0

Transitive closure matrix

A*	0	1	2	3
0	1	1	1	1
1	0	1	1	1
2	0	1	1	1
3	0	0	0	1

Reflexive transitive closure matrix

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